# Cauchy integrals for computational solutions of master equations 

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(Received 26 February 2015; revised 21 September 2015)


#### Abstract

Cauchy contour integrals are demonstrated to be effective in computationally solving master equations. A fractional generalization of a bimolecular master equation is one interesting application.


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http://journal.austms.org.au/ojs/index.php/ANZIAMJ/article/view/9345
gives this article, © Austral. Mathematical Soc. 2015. Published October 12, 2015, as part of the Proceedings of the 17th Biennial Computational Techniques and Applications Conference. ISSN 1446-8735. (Print two pages per sheet of paper.) Copies of this article must not be made otherwise available on the internet; instead link directly to this URL for this article.

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## 1 Introduction

A celebrated result of complex analysis is the Cauchy integral formula:

$$
f(a)=\frac{1}{2 \pi i} \int_{\Gamma} f(z)(z-a)^{-1} d z
$$

Here the function $f$ is analytic on a simple domain $\mathrm{D} \subset \mathbb{C}$ containing the smooth contour $\Gamma \subset \mathrm{D}$, which winds once counter-clockwise around the point a [32]. For the Laplace transform of $f, F(s) \equiv \mathcal{L}\{f\}=\int_{0}^{\infty} e^{-s t} f(t) d t$, the inverse Laplace transform

$$
\mathcal{L}^{-1}\{F\}(\mathrm{t})=\frac{1}{2 \pi \mathrm{i}} \int_{\gamma-\mathrm{i} \infty}^{\gamma+\mathrm{i} \infty} e^{\text {st }} \mathrm{F}(\mathrm{~s}) \mathrm{ds},
$$

comes via Cauchy's formula and is known as the Bromwich integral. The contour in this case is a vertical line parallel to the imaginary axis with real part $\gamma$ to the right of all singularities of F . By Cauchy's integral theorem, the integral is path independent so there is freedom to choose a different contour $\Gamma$ if that is more convenient. The inverse Laplace transform and all examples to come in this article involve integrands with a factor $e^{z}$ so the integrand is exponentially small in regions where $\operatorname{Re}(z)<0$. This observation has inspired numerical methods based on contours that pass through the left-half plane to take advantage of exponentially small integrands. Such Hankel contours resemble a sideways parabola (Figure 1) that encloses the negative real axis $(-\infty, 0]$, winding around the origin once.

Truncating the infinite contour $\Gamma$ to only a finite part, say $\operatorname{Re}(z)>-50$, introduces only an exponentially small error because of the $e^{z}$ factor. For

Figure 1: The parabolic contour $\Gamma$ to compute the Cauchy integral (2).

$\theta \in \mathbb{R}$ and $\mathrm{N}=2^{4}$, this article uses a parabola (Figure 1) optimised by Weideman and Trefethen [40, 43]:

$$
\begin{equation*}
z(\theta)=\mathrm{N}\left(0.1309-0.1194 \theta^{2}+0.25 i \theta\right) . \tag{1}
\end{equation*}
$$

John Butcher [4] and Alan Talbot [37] were amongst the first to suggest using the Cauchy formula numerically in this way to find inverse Laplace transforms.

The Cauchy integral formula generalizes to define a matrix function [13]: $2 \pi i f(A)=\int_{\Gamma} f(z)(z I-A)^{-1} d z$, (where I is the identity matrix). Indeed, it generalizes to operator settings [17, 8] but we consider only the case of a finite and bounded matrix $A$ with distinct real eigenvalues that are negative or zero: $\lambda_{i} \leqslant 0$. For example, put $f(z)=e^{z}$ to see the matrix exponential $e^{\mathcal{A}}$ as the inverse Laplace transform of the resolvent $(z I-\mathcal{A})^{-1}$. Multiply both sides by a vector $\boldsymbol{v}$ because (without explicitly forming a full matrix such as $f(A)$ ) we directly compute $f(A) v$ as the action of a matrix function on a
vector:

$$
\begin{equation*}
f(A) v=\frac{1}{2 \pi \mathrm{i}} \int_{\Gamma} f(z)(z \mathrm{I}-A)^{-1} v \mathrm{~d} z . \tag{2}
\end{equation*}
$$

Evaluating the integral involves solving shifted linear systems at nodes (dots in Figure 1) $z_{\mathrm{k}}=z\left(\theta_{\mathrm{k}}\right)$ on $\Gamma$ in (1), in a quadrature approximation to (2):

$$
\begin{equation*}
\mathrm{f}(\mathcal{A}) \boldsymbol{v} \approx \sum_{\mathrm{k}=1}^{\mathrm{N}} w_{k} \mathbf{u}_{\mathrm{k}} \quad \text { where } \quad\left(z_{\mathrm{k}} \mathrm{I}-\mathcal{A}\right) \mathbf{u}_{\mathrm{k}}=\boldsymbol{v} \tag{3}
\end{equation*}
$$

Experiments here use the trapezoidal-like methods of Weideman and Trefethen [43] and all involve a factor $e^{z_{k}}$. Weideman and Trefethen [43] discuss more details, such as nodes $z_{\mathrm{k}}$ and the quadrature weights $w_{\mathrm{k}}\left(z_{\mathrm{k}}\right)$.

Via (3) we compute two functions: an exponential function and a MittagLeffler function [26, 29]. Previous work in this field shows the approach is successful for parabolic partial differential equations [23, 34, 24]. Now we apply the approach to special matrices from chemistry [10, 41, 20].

## 2 A bimolecular master equation

Bimolecular reactions [3,5,35] between two chemical species $S_{1}$ and $S_{2}$ to form a third species $S_{3}$,

$$
\begin{equation*}
\mathrm{S}_{1}+\mathrm{S}_{2} \rightleftharpoons \mathrm{~S}_{3}, \tag{4}
\end{equation*}
$$

are now studied at single molecule resolution. A popular mathematical model is a continuous time Markov process, known as a chemical master equation, where states record the number of molecules of each species [10, 41, 20, 16, 11, 1, 6]. A state is $\left(n_{1}, n_{2}, n_{3}\right)$ when there are $n_{1}, n_{2}$ and $n_{3}$ molecules of species $S_{1}, S_{2}$ and $S_{3}$, respectively. The probability $p_{i}$ of state $i$ is recorded in the $\mathfrak{i t h}$ element of the vector $\mathbf{p}$. These probabilities evolve according to the system of linear differential equations

$$
\begin{equation*}
\frac{\mathrm{d}}{\mathrm{dt}} \boldsymbol{p}=A \boldsymbol{p} \quad \text { with solution } \quad \mathfrak{p}(\mathrm{t})=\mathrm{e}^{A \mathrm{t}} \mathbf{p}(0) \tag{5}
\end{equation*}
$$

According to this master equation, the probability of transitioning from state $j$ to state $i$ in time $d t$ is approximately given by the corresponding nonnegative off-diagonal entry: $A_{i j} d t$. Diagonal entries of $A$ ensure zero column sum.
All our examples start in the initial state $\left(n_{1}, n_{2}, n_{3}\right)=(M-1, M-1,0)$. State $\mathfrak{i}$ is $(M-i, M-i, i-1)$ for $\mathfrak{i}=1, \ldots M$. In our example (4), the forward reaction $\left(S_{1}+S_{2} \rightarrow S_{3}\right)$ rate is $c_{f} n_{1} n_{2}$, and the backward rate is $c_{b} n_{3}$. Here $c_{f}$ and $c_{b}$ are rate constants that depend on chemical and physical properties. In this example, $A_{i+1, i}=c_{f}(M-i)^{2}$ and $A_{i, i+1}=c_{b} i$. This gives rise to a family of $M \times M$ tridiagonal matrices. With $c_{f}=c_{b}=1$, the superdiagonal is $1,2, \ldots, M-1$ and the subdiagonal is $(M-1)^{2},(M-2)^{2}, \ldots, 1^{2}$. A small example $(M=6)$ is

$$
A=\left[\begin{array}{cccccc}
-25 & 1 & & & &  \tag{6}\\
25 & -17 & 2 & & & \\
& 16 & -11 & 3 & & \\
& & 9 & -7 & 4 & \\
& & & 4 & -5 & 5 \\
& & & & 1 & -5
\end{array}\right]
$$

All our figures use $M=101$ and $c_{b}=1$. Figures 2,3 and 4 set $c_{f}=1$. Figures 5, 6 and 7 set $\mathbf{c}_{f}=0.02$. The matrix exponential solution (5) is computed as $f(A t)$, with $f(z t)=e^{z t}$, by the approximation (3) to the Cauchy integral (2).

Trapezoidal rules such as in (3) generically exhibit low rates of convergence but in the special case of periodic integrands, the rate of convergence is spectacular [40, 38], and the error in (3) decreases exponentially with N [43]. With only $\mathrm{N}=2^{4}$, quadrature points in Figure 1 (just eight are needed in our cases of real solutions when symmetry is exploited) we get excellent accuracy at $t=1$ (Figure 2, bottom); using Matlab's expm as a reference solution, the maximum error across all components is $\approx 10^{-7}$.

However, at other $t$ values the numerical method produces large errors. For example, at $t=0.01$, Figure 2 (top) shows negative numbers that are

Figure 2: Numerical solution of bimolecular master equation (5) via the quadrature approximation (3) to the Cauchy integral (2). When $t=0.01$ the approximation leads to significant error (top). When $t=1$ the approximation is an accurate solution (bottom).


Figure 3: Resolvent norm of At on the parabolic contour $\Gamma$ (1) (Figure 1) as computed by Chebfun [7]. This resolvent norm is very large when $t=0.01$ (top), whereas the norm is approximately one when $t=1$ (bottom).



Figure 4: Level curves of the resolvent norm of At (6) as computed by EigTool [44] (minimum singular value $s_{\min }(z I-A t)$ shown on $\log$ scale). Eigenvalues are marked on the negative real axis. The parabolic contour $\Gamma$ (Figure 1) is visible when $t=0.01$ (top) but not when $t=1$ (bottom).

impossible in the true solution, which is always a nonnegative probability vector. To understand the cause of the error it is instructive to examine the norm of the resolvent on the contour (Figure 3, as computed by Chebfun [7]). It is mild, $\mathcal{O}(1)$, at $t=1$ but enormous, $\mathcal{O}\left(10^{8}\right)$, at $t=0.01$. Although the overall error ${ }^{1}$ comes from various sources [43, 42], Figure 4 suggests one source of error could be reduced by choosing a wider contour (such as a hyperbola) to avoid regions, known as the pseudospectra, where the resolvent is large [39]. For $\epsilon>0$, the $\epsilon$-pseudospectra is the region where $\left\|(z I-A)^{-1}\right\|>1 / \epsilon$ or, equivelently in the 2 -norm, where the minimum singular value $s_{\min }$ is small:

$$
\sigma_{\epsilon} \equiv\left\{z \in \mathbb{C}: s_{\min }(z I-A)<\epsilon\right\}
$$

Continuum approximations of master equations are related to convectiondiffusion equations. For example, Gillespie [10] points out that a natural finite difference approximation to a Fokker-Planck equation recovers exactly a master equation. Such convection-diffusion like equations are known to have numerical issues associated with pseudospectra [31, 42, 15, 39] so it is likely that chemical master equations also have pseudospectra of numerical significance. EigTool [44] confirms this for the bimolecular example (6) in Figure 4. Top ( $t=0.01$ ) and bottom $(t=1)$ plots are nearly identical because the pseudospectra of $A t$ is a scaled version of the pseudospectra of $A$ (real axis, imaginary axis and $s_{\min }$ are all multiplied by t ).

Estimates of the pseudospectra, such as Figure 4, are desirable because they guide the choice of computationally preferable contours in (2). The same arguments of Reddy and Trefethen [31, Section 5] and of Trefethen and Embree [39, Section 12] applied to $\mathcal{A}$ in (6) lead to a bound ${ }^{2}$

$$
\left\|(z I-A)^{-1}\right\| \leqslant \frac{\kappa}{|\operatorname{Im}(z)|}
$$

[^0]Future work will explore finer estimates and connections of master equation matrices (6) to twisted Toeplitz matrices [39]. One encouraging aspect of Figure 4 is that the resolvent is largest in the far left plane, where numerical evaluation on the contour is not usually required. Notice for example that our contour (Figure 1) is not visible at the larger scales on the bottom plot of Figure 4.

## 3 Application to a fractional master equation

Often motivated from the viewpoint of continuous-time random walks, there has been much recent interest in fractional models and associated numerical methods $[27,18,25,12,45,2,19,30]$. Using the Caputo fractional derivative

$$
D_{t}^{\alpha} f(t)=\frac{1}{\Gamma(1-\alpha)} \int_{0}^{t} \frac{f^{\prime}(s)}{(t-s)^{\alpha}} d s
$$

for $0<\alpha \leqslant 1$ a time-fractional generalisation of the master equation (5) is

$$
\begin{equation*}
D_{\mathrm{t}}^{\alpha} \mathbf{p}=A \mathbf{p} \quad \text { with solution } \quad \mathbf{p}(\mathrm{t})=\mathrm{E}_{\alpha}\left(A \mathrm{t}^{\alpha}\right) \mathbf{p}(0) \tag{7}
\end{equation*}
$$

where $E_{\alpha}$ is the one-parameter Mittag-Leffler function

$$
\mathrm{E}_{\alpha}(z)=\sum_{\mathrm{k}=0}^{\infty} \frac{z^{\mathrm{k}}}{\Gamma(\alpha \mathrm{k}+1)}
$$

The exponential is recovered at $\alpha=1$. The defining Markov features of $A$ ensure columns of $e^{A t}$ are probability vectors. An intuitive way to to see that $E_{\alpha}\left(A t^{\alpha}\right)$ shares this property with the exponential is via a representation of the Mittag-Leffler function as a mixture of exponentials, $E_{\alpha}(-t)=\int_{0}^{\infty} g(s) e^{-s t} d s$, where $g(s)$ is a nonnegative probability density. When computing $E_{\alpha}\left(A t^{\alpha}\right)$ as $f\left(A t^{\alpha}\right)$ via (2) and (3), the linear solutions are now related to $\left(z^{\alpha} I-A t^{\alpha}\right)^{-1}$ [43]. Numerical solutions via (3) for the usual exponential function $(\alpha=1)$ and for the Mittag-Leffler function $(\alpha=0.6)$
are compared in Figures 5 and 6. Unlike for the exponential (Figure 3, top), $\left\|\left(z^{\alpha} I-A t^{\alpha}\right)^{-1}\right\| \approx \mathcal{O}(1)$ is mild on $\Gamma$ (we are also seeing the resolvent on the wider contour $\Gamma^{\alpha}$ for $\alpha=0.6$ ), suggesting Mittag-Leffler evaluation is less sensitive to nonnormality for this example.

At very short timescales the reaction proceeds more quickly in the fractional model than in the more standard model that is not fractional (Figure 5, top), but at longer timescales the reaction proceeds more slowly in the fractional model (Figure 5, bottom). As $\mathrm{t} \rightarrow \infty$, Figure 6 shows both the standard model (5) and the fractional model (7) tend to the same stationary distribution $\boldsymbol{p}_{\infty}$. This is understood by letting $\mathcal{A}=\mathrm{V} \wedge \mathrm{V}^{-1}$ be the eigenvalue decomposition and comparing solutions as matrix functions via diagonalization: $f\left(A t^{\alpha}\right)=\operatorname{Vf}\left(\Lambda t^{\alpha}\right) V^{-1}$, with $f\left(\lambda_{j} t^{\alpha}\right)=E_{\alpha}\left(\lambda_{j} t^{\alpha}\right)$. Eigenvalues $\lambda_{j}$ of $A$, in the diagonal matrix $\Lambda$, are all negative except for a unique zero eigenvalue. For both the exponential function and the Mittag-Leffler function, $\mathrm{E}_{\alpha}(0)=1$ for $0<\alpha \leqslant 1$, so the column of the eigenvector matrix V corresponding to the zero eigenvalue, which is the stationary distribution $\mathbf{p}_{\infty}$, persists as $\mathrm{t} \rightarrow \infty$. All other eigenmodes decay because for $0<\alpha \leqslant 1$ and $\lambda<0$, $\mathrm{E}_{\alpha}\left(\lambda \mathrm{t}^{\alpha}\right) \rightarrow 0$ as $\mathrm{t} \rightarrow \infty$. The rate of decay is always exponential $\left(\approx e^{-\mathrm{t}}\right)$ for $\alpha=1$. However, when $0<\alpha<1$ asymptotics of the Mittag-Leffler function $E_{\alpha}\left(-t^{\alpha}\right)$ exhibit faster than exponential decay $\left(\approx e^{-t^{\alpha}}\right)$ for $t \ll 1$, and much slower decay $\left(\approx 1 / \mathrm{t}^{\alpha}\right)$ for large t . These are the familiar scalings of the Mittag-Leffler function, which behaves like a stretched exponential for small times and like an inverse power law for large times.

Monte Carlo simulation of fractional models by Gillespie-like algorithms [10] is possible by drawing from Mittag-Leffler waiting times, instead of from the usual exponential waiting times of a Markov process [14, 9, 33, 22]. A comparison of sample paths (Figure 7) reveals longer pauses in the fractional model associated with the heavy-tailed Mittag-Leffler waiting times. With $10^{5}$ samples, Monte Carlo estimates of the distribution are in good agreement (Figure 5 and 6 ) with solutions of (7) but slow for these examples: a modern computer takes $<1$ second to solve the fractional master equation in (7), or five minutes for $10^{5}$ simulations.

Figure 5: A fractional generalisation of a bimolecular master equation has solution in terms of a Mittag-Leffler function (7), which is compared here to the exponential solution of the usual master equation (5).

## $\mathbf{t}=\mathbf{0 . 1}$




Figure 6: A fractional generalisation of a bimolecular master equation has solution in terms of a Mittag-Leffler function (7), which is compared here to the exponential solution of the usual master equation (5).


## 4 Discussion

A number of areas are now identified for further research, including: stochastic subordination [21], more flexible physical models [12], exploration of the pseudospectra in the 1 -norm and $\infty$-norm [39], and the Toeplitz plus Hankel structures of fractional graph Laplacians or of fractional wave equations [36]. Finally, master equations in biology can involve high-dimensional problems in which matrices become so large that computing exponentials is not possible. Future work will extend the approaches here to larger scales by exploiting the parallelism that the Cauchy integral offers - the shifted linear systems $\left(z_{\mathrm{k}} \mathrm{I}-\mathcal{A}\right) \boldsymbol{u}_{\mathrm{k}}=\boldsymbol{v}$ of (3) may be solved independently and via iterative methods such as Krylov methods [28].

Figure 7: Two Monte Carlo simulations: one with exponential waiting times, and another with Mittag-Leffler waiting times. Histograms of many sample paths with Mittag-Leffler waiting times appear in Figures 5 and 6.


Conclusion Cauchy integrals are effective in computationally solving bimolecular master equations. A benefit of the approach is that it offers a framework for fractional generalisations of master equations. However, chemical master equations involve nonnormal matrices for which the resolvent is large in significant regions of the complex plane; progress with the Cauchy integral approach requires further study of the pseudospectra. In contrast, stochastic simulation of sample paths via Gillespie-like approaches remains possible even in the presence of nonnormality.

Acknowledgements The author thanks Christopher Angstmann, Kevin Burrage, Bruce Henry, Bill McLean, Gilbert Strang, and organisers of ctac, and Canberra, 2014, for helpful discussions.

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[^0]:    ${ }^{1}$ This is not entirely fair to the method; the contour should allow dependence on $t$. Moreover, the method was designed with self-adjoint problems (unlike A) in mind.
    ${ }^{2}$ Here $\kappa$ is the condition number of a matrix that symmetrizes $A$. For fixed $M$, this bound confines the pseudospectra to a strip of finite width about the real axis but unfortunately k grows extremely fast with $M$.

