Analytical and numerical solutions for the time and space-symmetric fractional diffusion equation

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Abstract

We consider a time and space-symmetric fractional diffusion equation (TSS-FDE) under homogeneous Dirichlet conditions and homogeneous Neumann conditions. The TSS-FDE is obtained from the standard diffusion equation by replacing the first-order time derivative by a Caputo fractional derivative, and the second order space derivative by a symmetric fractional derivative. First, a method of separating variables expresses the analytical solution of the TSS-FDE in terms of the Mittag-Leffler function. Second, we propose two numerical methods to approximate the Caputo time fractional derivative: the finite difference method; and the Laplace transform method. The symmetric space fractional derivative is approximated using the matrix transform method. Finally, numerical results demonstrate the effectiveness of the numerical methods and to confirm the theoretical claims.

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1 Introduction

A growing number of works in science and engineering deal with dynamical systems described by fractional order equations that involve derivatives and integrals of non-integer order [1, 3, 6, 16]. These new models are more adequate than the previously used integer order models, because fractional order derivatives and integrals describe the memory and hereditary properties of different substances [12]. This is the most significant advantage of the fractional order models in comparison with integer order models, in which such effects are neglected. In the context of flow in porous media, fractional space derivatives model large motions through highly conductive layers or fractures, while fractional time derivatives describe particles that remain motionless for extended periods of time [7].

In this article, we consider the following time and space-symmetric fractional diffusion equation (TSS-FDE):

$${}_{t}D_{*}^{\alpha}\mathfrak{u}(x,t) = -K_{\beta}(-\Delta)^{\beta/2}\mathfrak{u}(x,t), \quad 0 \le t \le T, \quad 0 \le x \le L, \qquad (1)$$

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subject to either homogeneous Dirichlet boundary conditions, or homogeneous Neumann boundary conditions

$$u(0,t) = u(L,t) = 0$$
, or $\frac{\partial u}{\partial x}(0,t) = \frac{\partial u}{\partial x}(L,t) = 0$, (2)

and the initial condition

$$\mathbf{u}(\mathbf{x},\mathbf{0}) = \mathbf{g}(\mathbf{x})\,,\tag{3}$$

where u(x, t) is a solute concentration field and K_{β} represents the dispersion coefficient. The operator ${}_{t}D^{\alpha}_{*}$ is the Caputo time fractional derivative of order α ($0 < \alpha < 1$), with starting point at t = 0, defined as [12]

$${}_{t}D_{*}^{\alpha}u(x,t) = \frac{1}{\Gamma(1-\alpha)} \int_{0}^{t} \frac{\partial u(x,\eta)}{\partial \eta} \frac{d\eta}{(t-\eta)^{\alpha}}.$$
 (4)

The symmetric space fractional derivative $-(-\Delta)^{\beta/2}$ of order β $(1 < \beta \leq 2)$ is defined by Gorenflo and Mainardi [2], where Δ is the Laplacian operator.

Physical considerations of a fractional diffusion equation restrict $0 < \alpha < 1$ and $1 < \beta \leq 2$, and we assume $K_{\beta} > 0$ so that the flow is from left to right. The physical meaning of using homogeneous Dirichlet boundary conditions is that the boundary is set far enough away from an evolving plume such that no significant concentrations reach that boundary [9, 10]. Also, by assuming homogeneous Dirichlet boundary conditions, we derive that the Riesz fractional derivative is equivalent to the fractional power of Laplacian operator [14], that is, $\partial^{\beta} u(\mathbf{x}, t)/\partial |\mathbf{x}|^{\beta} = -(-\Delta)^{\beta/2} u(\mathbf{x}, t)$. The physical meaning of using homogeneous Neumann boundary conditions is that the tracer moves freely through the boundaries [11].

In the case of $\alpha = 1$ and $\beta = 2$, the TSS-FDE (1) reduces to the classical diffusion equation. For $0 < \alpha < 1$ and $\beta = 2$, the TSS-FDE (1) models subdiffusion due to particles having heavy tailed resting times, whereas for $\alpha = 1$ and $1 < \beta < 2$ the TSS-FDE (1) corresponds to the Lévy process [16].

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Hence, the solution of TSS-FDE (1) is important for describing the competition between these two anomalous diffusion processes. The TSS-FDE was first introduced by Zaslavsky [15] to model Hamiltonian chaos. More recently, an important application of TSS-FDE arose in finance [8], where coupled continuous time random walk (CTRW) models were used to describe the movement of log-prices. In these coupled CTRW models, the probability density functions for the limiting stochastic process solve TSS-FDE.

2 Analytical solutions

In this section, using the method of separation of variables, the analytical solution of TSS-FDE (1)-(3) is first derived under homogeneous Dirichlet boundary conditions. For homogeneous Neumann conditions, a similar method can be used to derive the analytical solution.

Setting u(x,t) = X(x)T(t) and substituting into (1) yields

$${}_{t}D_{*}^{\alpha}X(x)T(t) + K_{\beta}(-\Delta)^{\beta/2}X(x)T(t) = 0.$$

Letting $-\omega$ be the separation constant we obtain two fractional ordinary linear differential equations for X(x) and T(t), respectively as

$$(-\Delta)^{\beta/2} X(x) - \omega X(x) = 0, \qquad (5)$$

$$_{t}D_{*}^{\alpha}T(t) + K_{\beta}\omega T(t) = 0.$$
(6)

Following Ilić et al.'s [4] definition of the fractional Laplacian $(-\Delta)^{\beta/2}$ defined on a bounded region, (5) is expressed as

$$\sum_{n=1}^{\infty} c_n (\lambda_n^2)^{\beta/2} x_n + \omega_n \sum_{n=1}^{\infty} c_n x_n = 0.$$
 (7)

Hence, under homogeneous Dirichlet conditions, the eigenvalues of (5) are $\omega_n = \lambda_n^\beta = (n\pi/L)^\beta$ for n = 1, 2, ..., and the corresponding eigenfunctions

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are nonzero constant multiples of $x_n = \sin(n\pi x/L)$. For homogeneous Neumann conditions, the eigenvalues are $\omega_n = \lambda_n^\beta = (n\pi/L)^\beta$ for n = 0, 1, 2, ..., and the corresponding eigenfunctions are $x_n = \cos(n\pi x/L)$.

Next, we seek a solution of the TSS-FDE (1) under homogeneous Dirichlet conditions in the form

$$u(x,t) = \sum_{n=1}^{\infty} T_n(t) \sin\left(\frac{n\pi x}{L}\right) \,. \tag{8}$$

Substituting (8) into (1) yields

$$_{t}D_{*}^{\alpha}T_{n}(t) = -K_{\beta}\omega_{n}T_{n}(t). \qquad (9)$$

Since u(x, t) must also satisfy the initial conditions (3)

$$\sum_{n=1}^{\infty} T_n(0) \sin\left(\frac{n\pi x}{L}\right) = g(x), \quad 0 \le x \le L,$$
(10)

and therefore

$$T_n(0) = \frac{2}{L} \int_0^L g(x) \sin\left(\frac{n\pi x}{L}\right) dx, \quad n = 1, 2, \dots.$$
(11)

For each value of n, (9) and (11) compose a fractional initial value problem. Applying the Laplace transform to (9), we obtain

$$\widetilde{\mathsf{T}}_{\mathsf{n}}(s) = \frac{s^{\alpha-1}\mathsf{T}_{\mathsf{n}}(0)}{s^{\alpha} + \mathsf{K}_{\beta}\omega_{\mathsf{n}}} \,. \tag{12}$$

By using the known inverse Laplace transform [13]

$$\mathsf{E}_{\alpha}(-\omega \mathsf{t}^{\alpha}) = \mathcal{L}^{-1}\left\{\frac{\mathsf{s}^{\alpha-1}}{\mathsf{s}^{\alpha}+\omega}\right\}, \quad \mathfrak{R}(\mathsf{s}) > |\omega|^{1/\alpha}, \tag{13}$$

we obtain the analytical solution of TSS-FDE (1) under homogeneous Dirichlet conditions as

$$u(x,t) = \sum_{n=1}^{\infty} T_n(t) \sin\left(\frac{n\pi x}{L}\right) = \sum_{n=1}^{\infty} E_{\alpha}(-K_{\beta}\omega_n t^{\alpha})T_n(0) \sin\left(\frac{n\pi x}{L}\right) , \quad (14)$$

where $T_n(0)$ is given in (11), and $E_{\alpha}(z)$ is the Mittag–Leffler function [12]

$$\mathsf{E}_{\alpha}(z) = \sum_{n=0}^{\infty} \frac{z^n}{\Gamma(an+1)}, \quad \alpha > 0.$$
 (15)

Here, when $\alpha = 1$, the solution (14) corresponds precisely with the results derived for the Riesz space fractional diffusion equation [14].

Similarly, the analytical solution of TSS-FDE (1) under homogeneous Neumann conditions is

$$\begin{aligned} \mathfrak{u}(\mathbf{x},t) &= \sum_{n=0}^{\infty} \mathsf{T}_{n}(t) \cos\left(\frac{n\pi x}{L}\right) \\ &= \frac{1}{2} \mathsf{T}_{0}(0) + \sum_{n=1}^{\infty} \mathsf{E}_{\alpha}(-\mathsf{K}_{\beta}\omega_{n}t^{\alpha}) \mathsf{T}_{n}(0) \cos\left(\frac{n\pi x}{L}\right) , \end{aligned}$$
(16)

where $T_n(0) = (2/L) \int_0^L g(x) \cos(n\pi x/L) dx$, n = 0, 1, 2, ..., and we have used the result that $E_{\alpha}(0) = 1$.

3 Numerical methods

In this section, we present two numerical schemes to simulate the solution behaviour of TSS-FDE (1)-(3). In Section 3.1, a finite difference method (FDM) and the matrix transform method (MTM) are used to discretize the Caputo time fractional derivative and the symmetric space fractional derivative, respectively. In Section 3.2, using the Laplace transform method (LTM)

together with the MTM, we transfer the TSS-FDE (1) into a discrete system describing the evolution of u(x, t) in space and time.

Using time stepping methods in the fractional case requires the storage of all previous time steps. The difficulty in solving fractional differential equations, particularly where the application area requires a solution to be given over a long time interval, is essentially because fractional derivatives are non-local operators. The so-called non-local property means that the next state of a system not only depends on its current state, but also on the historical states starting from the initial time. This property is closer to reality and is the main reason why fractional Calculus has become more and more useful. To overcome this difficulty, some researchers explore techniques for reducing computational cost that keeps the error under control. The simplest approach is to disregard the tail of the integral and to integrate only over a fixed period of recent history. This is commonly referred to as the 'short-memory' principle, and is described by Podlubny [12]. Here, we only consider the full memory case.

3.1 Finite difference method with matrix transform method

Let $x_l := lh$, l = 0, 1, ..., M, where h := L/M is the space step; $t_n := n\tau$, n = 0, 1, ..., N, where $\tau := T/N$ is the time step; and u_l^n denote the numerical approximation of $u(x_l, t_n)$. Adopting the FDM given by Lin & Xu [5], we discretize the Caputo time fractional derivative as

$${}_{t}D_{*}^{\alpha}u_{l}^{n+1} = \frac{\tau^{-\alpha}}{\Gamma(2-\alpha)}\sum_{j=0}^{n}b_{j}\left[u_{l}^{n+1-j} - u_{l}^{n-j}\right] + O(\tau^{2-\alpha}), \quad (17)$$

written in matrix form

$${}_{t}D_{*}^{\alpha}U^{n+1} = \frac{1}{\mu_{0}}\sum_{j=0}^{n} b_{j} \left[U^{n+1-j} - U^{n-j} \right] + O(\tau^{2-\alpha}), \qquad (18)$$

where $\mu_0 = \tau^{\alpha} \Gamma(2 - \alpha)$, $b_j = (j + 1)^{1-\alpha} - j^{1-\alpha}$, j = 0, 1, 2, ..., n. Utilising the theory described by Ilić et al. [4], we find a matrix representative for the fractional Laplacian operator

$$-(-\Delta)^{\beta/2}\mathbf{U} \approx -\frac{1}{\mathbf{h}^{\beta}}\mathbf{A}^{\beta/2}\mathbf{U}, \qquad (19)$$

where $\mathbf{A} = \text{tridiag}(-1, 2, -1) \in \mathbb{R}^{(M-1) \times (M-1)}$ under homogeneous Dirichlet conditions, or

$$\mathbf{A} = \begin{bmatrix} 1 & -1 & & \\ -1 & 2 & -1 & & \\ & \ddots & \ddots & \ddots & \\ & & -1 & 2 & -1 \\ & & & & -1 & 1 \end{bmatrix}_{(M+1)\times(M+1)}$$

under homogeneous Neumann conditions. Since the matrix \mathbf{A} is symmetric positive definite (SPD), there exits a nonsingular matrix \mathbf{P} that orthogonally diagonalises \mathbf{A} as

$$\mathbf{A} = \mathbf{P} \mathbf{\Lambda} \mathbf{P}^{\mathsf{T}},\tag{20}$$

where $\Lambda = \text{diag}(\lambda_1, \lambda_2, \dots, \lambda_{M-1})$ under homogeneous Dirichlet conditions or $\Lambda = \text{diag}(\lambda_0, \lambda_1, \dots, \lambda_M)$ under homogeneous Neumann conditions, λ_i ($i = 0, 1, 2, \dots, M$) being the eigenvalues of **A**. Thus, the fractional Laplacian can be expressed in terms of its spectral decomposition as

$$-(-\Delta)^{\beta/2}\mathbf{U} \approx -\frac{1}{\mathbf{h}^{\beta}}\mathbf{P}\Lambda^{\beta/2}\mathbf{P}^{\mathsf{T}}\mathbf{U}\,.$$
 (21)

Now, combining (18) with (21), we obtain the following numerical difference approximation of the TSS-FDE (1):

$$\frac{1}{\mu_0} \sum_{j=0}^{n} b_j \left[\mathbf{U}^{n+1-j} - \mathbf{U}^{n-j} \right] = -\eta_\beta \mathbf{P} \Lambda^{\beta/2} \mathbf{P}^\mathsf{T} \mathbf{U}^{n+1} \,, \tag{22}$$

where $\eta_{\beta} = K_{\beta}/h^{\beta}$. After simplification,

$$\left[\mathbf{b}_{0}\mathbf{I}+\boldsymbol{\mu}_{0}\boldsymbol{\eta}_{\beta}\mathbf{P}\boldsymbol{\Lambda}^{\beta/2}\mathbf{P}^{\mathsf{T}}\right]\mathbf{U}^{\mathfrak{n}+1}=\sum_{j=0}^{\mathfrak{n}-1}(\mathbf{b}_{j}-\mathbf{b}_{j+1})\mathbf{U}^{\mathfrak{n}-j}+\mathbf{b}_{\mathfrak{n}}\mathbf{U}^{0}\,,\qquad(23)$$

where \mathbf{U}^{0} is the matrix representation of the initial value $g(\mathbf{x})$.

3.2 Laplace transform method with matrix transform method

We now consider an alternate strategy for approximating the fractional ODE system associated with the TSS-FDE (1), when the approximation for the fractional Laplacian is given by (19):

$${}_{t}\mathbf{D}_{*}^{\alpha}\mathbf{U}^{n} = -\eta_{\beta}\mathbf{A}^{\beta/2}\mathbf{U}^{n}.$$
(24)

Applying the Laplace transform to (24) with $\widetilde{\mathbf{U}}^n = \mathcal{L}\{\mathbf{U}^n(t)\}$ yields

$$\widetilde{\mathbf{U}}^{n} = \left[\mathbf{s}\mathbf{I} + \mathbf{s}^{1-\alpha}\eta_{\beta}\mathbf{A}^{\beta/2}\right]^{-1}\mathbf{U}^{0}.$$
(25)

Since \mathbf{A} is SPD and has the orthogonal diagonalisation (20), we obtain

$$\mathbf{U}^{n} = \mathbf{P}\mathcal{L}^{-1}\left\{\left(\mathbf{s}\mathbf{I} + \mathbf{s}^{1-\alpha}\eta_{\beta}\Lambda^{\beta/2}\right)^{-1}\right\}\mathbf{P}^{\mathsf{T}}\mathbf{U}^{\mathsf{0}}.$$
 (26)

Recalling (13) and applying the inverse Laplace transform for each of the eigenvalues, we obtain the second numerical scheme for approximating the TSS-FDE (1) as

$$\mathbf{U}^{n} = \mathbf{P} \mathsf{E}_{\alpha}(-\mathbf{t}_{n}^{\alpha} \eta_{\beta} \Lambda^{\beta/2}) \mathbf{P}^{\mathsf{T}} \mathbf{U}^{0}, \qquad (27)$$

where $E_{\alpha}(z)$ is the Mittag–Leffler function defined in (15).

4 Numerical examples



FIGURE 1: Comparison of the numerical solutions with the exact solution at different times t = 0.1, 1.0, 5.0 for (a) the TSS-FDE (28)-(30), and (b) the TSS-FDE (32)-(34), with $\alpha = 0.5$, $\beta = 1.5$, M = 50, N = 100.

4 Numerical examples

In this section, we provide two examples of the TSS-FDE to assess the accuracy of the two numerical schemes proposed in Section 3, and to illustrate the solution behaviour that arises as we change from integer to fractional order in time and space.

Example 1 Considering the following TSS-FDE with homogeneous Neumann boundary conditions:

$${}_{t}D^{\alpha}_{*}\mathfrak{u}(\mathbf{x},t) = -(-\Delta)^{\beta/2}\mathfrak{u}(\mathbf{x},t), \quad 0 \le t \le \mathsf{T}, \quad 0 \le \mathbf{x} \le \pi, \qquad (28)$$

$$\frac{\partial u}{\partial x}(0,t) = \frac{\partial u}{\partial x}(L,t) = 0, \qquad (29)$$

$$u(\mathbf{x},\mathbf{0}) = \mathbf{x}^2 \left(\frac{3}{2}\pi - \mathbf{x}\right) \,. \tag{30}$$

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TABLE 1: Maximum	errors at $t = 1$	with fixed	time step 7	$\tau = 0.01$.
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h	LTM-MTM	FDM-MTM
$\pi/8$	1.73 E-02	1.98 E-02
$\pi/16$	4.33 E-03	7.05 E-03
$\pi/32$	1.08 E-03	4.00 E-03
$\pi/64$	2.72 E-04	3.28 E-03

TABLE 2: Maximum errors at t = 1 with fixed space step $h = \pi/50$.

τ	LTM-MTM	FDM-MTM
1/10	4.44 E-04	3.43 E-02
1/25	4.44 E-04	1.31 E-02
1/50	4.44 E-04	6.60 E- 03
1/100	4.44 E-04	3.44 E-03

Following the solution method (16) derived in Section 2, the analytical solution of TSS-FDE (28)-(30) is

$$\mathfrak{u}(\mathbf{x},t) = \frac{\pi^3}{4} + \sum_{n=1}^{\infty} \frac{12[(-1)^n - 1]}{\pi n^4} \mathsf{E}_{\alpha}(-n^{\beta}t^{\alpha})\cos(nx) \,. \tag{31}$$

Figure 1(a) shows that both numerical solution schemes provide a good match with the analytical solution (31) at different times t, with $\alpha = 0.5$, $\beta = 1.5$, M = 50, N = 100.

Example 2 Consider the following TSS-FDE with homogeneous Dirichlet boundary conditions:

$${}_{t}D^{\alpha}_{*}\mathfrak{u}(\mathbf{x},t) = -(-\Delta)^{\beta/2}\mathfrak{u}(\mathbf{x},t), \quad 0 \le t \le \mathsf{T}, \quad 0 \le \mathbf{x} \le \pi, \qquad (32)$$

$$u(0,t) = u(\pi,t) = 0,$$
 (33)

$$u(x,0) = x^2(\pi - x).$$
 (34)

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FIGURE 2: Numerical solutions at t = 1.0 for the TSS-FDE (32)–(34) with: (a) $0 < \alpha < 1$, $\beta = 1.5$; and (b) $\alpha = 0.5$, $1 < \beta \le 2$ (b).

According to (14), the exact solution of TSS-FDE (32)-(34) is

$$u(x,t) = \sum_{n=1}^{\infty} \frac{8(-1)^{n+1} - 4}{n^3} \mathsf{E}_{\alpha}(-n^{\beta}t^{\alpha})\sin(nx) \,. \tag{35}$$

Figure 1(b) shows that both numerical solution schemes provide a good match with the analytical solution (35) at different times t, with $\alpha = 0.5$, $\beta = 1.5$, M = 50, N = 100. Furthermore, Tables 1 and 2, show that the maximum errors are decreasing as the spatial and temporal nodes increase. Especially, the LTM-MTM is more accurate than the FDM-MTM because it is exact in time. The error observed in the tables for the LTM-MTM is only associated with the spatial discretisation error. More rigorous analyses on stability and convergence will be investigated in future work.

Figure 2(a) displays the solution profiles of the TSS-FDE (32)–(34) over space for $0 < \alpha < 1$, $\beta = 1.5$ at t = 1.0. As α is increased over the interval (0, 1) the solution profile diminishes in magnitude and becomes slightly more skewed. The solution profiles for selected values of β with $\alpha = 0.5$ at t =1.0 are shown in Figure 2(b). The process featured with $\beta = 1.2, 1.4, 1.6, 1.8$

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is slightly more skewed to the right than that with $\beta = 2.0$. Furthermore, the solution continuously depends on the time and space fractional derivatives.

5 Conclusions

An analytical solution and two numerical schemes for approximating the TSS-FDE were derived under both homogeneous Dirichlet and Neumann boundary conditions. These solution techniques can be applied to other fractional partial differential equations. In future research, we will report the stability and convergence analyses of the proposed numerical methods.

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